Université de Nice Sophia-Antipolis Master MathMods - Finite Elements - 2008/2009 V. Dolean

# Exercises - Chapter 0 (correction)

#### Exercise 1.

Find the "stiffness" matrix  $\mathbf{K}$  for linear basis functions. If the right hand side f is piecewise linear i.e.

$$f(x) = \sum_{j=1}^{n} f_j \phi_j(x)$$

determine the matrix  $\mathbf{M}$  called "mass" matrix such that :  $\mathbf{KU} = \mathbf{MF}$ .

Answer. The linear basis functions are given by :

$$\phi_i(x) = \begin{cases} \frac{x - x_{i-1}}{h_i}, x \in [x_{i-1}, x_i], \\ \frac{x_{i+1} - x}{h_{i+1}}, x \in [x_i, x_{i+1}], \\ 0, x \notin [x_{i-1}, x_{i+1}]. \end{cases}$$

According to the expression of the "stiffness" matrix we can write :

$$K_{ii} = \int_0^1 (\phi'_i)^2(x) dx = \int_{x_{i-1}}^{x_i} (\phi'_i)^2(x) dx + \int_{x_i}^{x_i+1} (\phi'_i)^2(x) dx = \frac{1}{h_i} + \frac{1}{h_{i+1}}.$$
  

$$K_{i,i+1} = K_{i+1,i} = \int_0^1 \phi'_i(x) \phi'_{i+1}(x) dx = \int_{x_i}^{x_i+1} \phi'_i(x) \phi'_{i+1}(x) dx = -\frac{1}{h_{i+1}}.$$

all the other elements being null since in all the other cases the basis functions  $\phi_i$  and  $\phi_j$  cannot be simultaneously non-zero. The right hand side can be written as :

$$b_i = \int_0^1 f(x)\phi_i(x)dx = \sum_{j=1}^n f_j \int_0^1 \phi_i(x)\phi_j(x)dx = \sum_{j=1}^n M_{ij}f_j, \ M_{ij} = \int_0^1 \phi_i(x)\phi_j(x)dx.$$

Thus, the "mass" matrix is formed by the elements  $M_{ij}$  which can be computed as follows (by performing a variable change  $x = x_{i-1} + th$  in the integral on  $[x_{i-1}, x_i]$  and  $x = x_i + th$ in the integral on  $[x_i, x_{i+1}]$ ):

$$\begin{split} M_{ii} &= \int_0^1 \phi_i^2(x) dx = \int_{x_{i-1}}^{x_i} \phi_i^2(x) dx + \int_{x_i}^{x_i+1} \phi_i^2(x) dx \\ &= h_i \int_0^1 t^2 dt + h_{i+1} \int_0^1 (1-t)^2 dt = \frac{h_i + h_{i+1}}{3} \\ M_{i,i+1} &= M_{i+1,i} = \int_0^1 \phi_i(x) \phi_{i+1}(x) dx = \int_{x_i}^{x_i+1} \phi_i(x) \phi_{i+1}(x) dx = h_{i+1} \int_0^1 (1-t) t dt = \frac{h_{i+1}}{6} \end{split}$$

all the other elements being null since in all the other cases the basis functions  $\phi_i$  and  $\phi_j$  cannot be simultaneously non-zero.

#### Exercise 2.

Give the weak formulation for the two-point boundary value problem :

$$\begin{cases} -u'' + u = f, x \in (0, 1), \\ u(0) = u(1) = 0. \end{cases}$$

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**Answer**. Mutiplying the equation inside the domain by a test function v and by integrating by parts we get :

$$\int_0^1 uv + u'v' = \int_0^1 fv, \ a(u,v) := \int_0^1 uv + u'v'$$

The weak formulation can be written as :

find 
$$u \in V = \{v \in L^2(0,1) : v(0) = v(1) = 0\}$$
, such that  $a(u,v) = (f,v), \forall v \in V$ .

### Exercise 3.

Explain what is wrong in both variational and classical setting for the problem :

$$\begin{cases} -u'' = f, x \in (0, 1), \\ u'(0) = u'(1) = 0 \end{cases}$$

that is explain in both contexts why this problem is not well-posed.

**Answer**. For the classical setting we can see that is u is solution of the problem u + C (where C is a constant) is also solution. Therefore the problem is not well-posed. The weak formulation can be written as :

find 
$$u \in V = L^2(0, 1)$$
, such that  $\int_0^1 u'v' = (f, v), \, \forall v \in V.$ 

If we put v = C (where C is a constant) we get that  $\int_0^1 f = 0$ , that means if f doesn't respect this condition the problem has no solution (this is called compatibility condition). If the condition is fulfilled, the solution is defined only up to a constant.

#### Exercise 4.

Show that piecewise quadratics have nodal basis consisting of values at nodes  $x_i$  together with the midpoints  $\frac{1}{2}(x_i + x_{i+1})$ . Calculate the stiffness matrix for these elements.

**Answer**. We denote by  $\phi_{2i}$  the basis functions associated to  $x_i$  and by  $\phi_{2i+1}$  those associated to the midpoint  $\frac{1}{2}(x_i + x_{i+1})$ . They are given by :

$$\phi_{2i}(x) = \begin{cases} \frac{2x - x_{i-1} - x_i}{h_i} \cdot \frac{x - x_{i-1}}{h_i} & x \in [x_{i-1}, x_i], \\ \frac{2x - x_i - x_{i+1}}{h_{i+1}} \cdot \frac{x - x_{i+1}}{h_{i+1}}, & x \in [x_i, x_{i+1}], \\ 0, x \notin [x_{i-1}, x_{i+1}]. \end{cases}, \ \phi_{2i+1}(x) = \begin{cases} 4\frac{x - x_i}{h_{i+1}} \cdot \frac{x_{i+1} - x}{h_{i+1}}, & x \in [x_i, x_{i+1}], \\ 0, x \notin [x_i, x_{i+1}]. \end{cases}$$

The stiffness matrix is again symmetric, with at most 5 non-zero elements on each line which can be computed as follows (by performing a variable change  $x = x_{i-1} + th$  in the integral on  $[x_{i-1}, x_i]$  and  $x = x_i + th$  in the integral on  $[x_i, x_{i+1}]$ ):

$$\begin{split} K_{2i,2i} &= \int_0^1 (\phi'_{2i})^2 (x) dx = \int_{x_{i-1}}^{x_i} (\phi'_{2i})^2 (x) dx + \int_{x_i}^{x_i+1} (\phi'_{2i})^2 (x) dx, \\ &= \frac{1}{h_i} \int_0^1 (4t-1)^2 dt + \frac{1}{h_{i+1}} \int_0^1 (4t-3)^2 dt = \frac{7}{3} \left(\frac{1}{h_i} + \frac{1}{h_{i+1}}\right), \\ K_{2i,2(i+1)} &= K_{2(i+1),2i} = \int_{x_i}^{x_i+1} \phi'_{2i} (x) \phi'_{2(i+1)} (x) dx = \frac{1}{h_{i+1}} \int_0^1 (4t-3)(4t-1) dt = \frac{1}{3h_{i+1}}, \\ K_{2i+1,2i+1} &= \int_{x_i}^{x_i+1} (\phi'_{2i+1})^2 (x) dx = \frac{1}{h_{i+1}} \int_0^1 16(2t-1)^2 dt = \frac{16}{3h_{i+1}}, \\ K_{2i,2i+1} &= K_{2i+1,2i} = \int_{x_i}^{x_i+1} \phi'_{2i} (x) \phi'_{2i+1} (x) dx = \frac{1}{h_{i+1}} \int_0^1 (4t-1)(4-8t) dt = -\frac{8}{3h_{i+1}}. \end{split}$$

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Exercise 5. Let  $h = \max_{1 \le i \le n} (x_i - x_{i-1})$ . Then,

$$||u - u_I|| \le Ch ||u''||, \, \forall u \in V_{\underline{s}}$$

where C is independent of h and u.

Hint : Use first the *homogeneity argument*, then show that :

$$\int_{0}^{1} w(x)^{2} dx \leq \tilde{c} \int_{0}^{1} w'(x)^{2} dx$$
(1)

by utilizing the fact that w(0) = 0. How small can you make  $\tilde{c}$  if you use both w(0) = 0 and w(1) = 0?

**Answer**. In the following we will use the *homogeneity argument* as in the lecture. According to the definition of the two norms, it is sufficient to prove the estimate piecewise, i.e.:

$$\int_{x_{j-1}}^{x_j} (u - u_I)'(x)^2 dx \le c(x_j - x_{j-1})^2 \int_{x_{j-1}}^{x_j} u''(x) dx$$

with  $C = \sqrt{c}$ . This inequality can be re-written in terms of error by denoting :  $e = u - u_I$  (note that  $u_I$  is piecewise linear and therefore its second derivative cancels) and then by performing a variable change  $x = x_{j-1} + t(x_j - x_{j-1})$  (an affine mapping from the interval  $[x_{j-1}, x_j]$  to [0, 1]) as follows :

$$\int_0^1 \tilde{e}(t)^2 dt \le c \int_0^1 \tilde{e}''(t) dt, \ \tilde{e}(t) = e(x_{j-1} + t(x_j - x_{j-1})).$$

Now, using some results of the lecture, it is enough to prove (1) for  $w = \tilde{e}$ . Note that w(0) = w(1) = 0 since the interpolation error will be zero at all nodes. Therefore :

$$w(x) = \int_0^x w'(t)dt$$

by using Schwarz' inequality we get :

$$\begin{split} \int_0^1 w(x)^2 dx &= \int_0^1 \left( \int_0^x 1 \cdot w'(t) dt \right)^2 dx \le \int_0^1 \left( \int_0^x dt \right) \cdot \left( \int_0^x w'(t)^2 dt \right) dx \\ &\le \int_0^1 x \cdot \left( \int_0^x w'(t)^2 dt \right) dx \le \int_0^1 x \cdot \left( \int_0^1 w'(t)^2 dt \right) dx \\ &= \left( \int_0^1 w'(t)^2 dt \right) \cdot \int_0^1 x dx = \frac{1}{2} \int_0^1 w'(t)^2 dt, \end{split}$$

the constant is thus  $\tilde{c} = \frac{1}{2}$ .

If w(0) = w(1) = 0, we can consider this function as periodic with period T = 1 and write its Fourier series as follows :

$$w(x) = \sum_{k} a_k \sin(k\pi x) = \sum_{k \neq 0} a_k \sin(k\pi x) \Rightarrow w'(x) = \sum_{k \neq 0} k\pi a_k \cos(k\pi x)$$

Using Parseval's equality we get :

$$\int_0^1 w(x)^2 dx = \frac{1}{2} \sum_{k \neq 0} a_k^2, \ \int_0^1 w'(x)^2 dx = \frac{1}{2} \sum_{k \neq 0} (k\pi)^2 a_k^2,$$

which proves the optimal inequality (the best  $\tilde{c} = \frac{1}{\pi^2}$ ):

$$\int_0^1 w(x)^2 dx \le \frac{1}{\pi^2} \int_0^1 w'(x)^2 dx$$

0

#### Exercise 6.

We denote  $a(u,v) = \int_0^1 u'(x)v'(x)dx$  and  $V = \{v \in L^2(0,1); a(v,v) < \infty, v(0) = 0\}$ . Prove the following *coercivity* results :

$$||v||^2 + ||v'||^2 \le Ca(v, v), \, \forall v \in V$$

Give a value for C.

**Answer**. Using the previous exercise it is easy to see that :

$$||v|| \le c||v'||, \ c = \frac{1}{2} \Rightarrow ||v||^2 + ||v'||^2 \le (c^2 + 1)||v'||^2 = (c^2 + 1)a(v,v) \Rightarrow C = \frac{5}{4}$$

Furthermore, if the space V were given by  $V = \{v \in L^2(0,1); a(v,v) < \infty, v(0) = v(1) = 0\}$ , then C attains its optimal value  $C = \frac{1 + \pi^4}{\pi^4}$ .

### Exercise 7.

Consider the difference method represented by :

$$-\frac{2}{h_i + h_{i+1}} \left( \frac{U_{i+1} - U_i}{h_{i+1}} - \frac{U_i - U_{i-1}}{h_i} \right) = f(x_i).$$
(2)

Prove that  $\tilde{u}_S = \sum_i U_i \phi_i$  satisfies the following :

$$a(\tilde{u}_S, v) = Q(fv), \, \forall v \in S, \, a(u, v) = \int_0^1 u'(x)v'(x)dx$$

where S consists of piecewise linears and Q denotes the quadrature approximation based on the trapezoidal rule :

$$Q(w) = \sum_{i=0}^{n} \frac{h_i + h_{i+1}}{2} w(x_i)$$

We further define  $h_0 = h_{n+1} = 0$  for simplicity of notation.

**Answer**. The relation (2) can be re-written as :

$$\mathbf{K}U = \mathbf{F}, \ \mathbf{F} = \left(\frac{h_i + h_{i+1}}{2}f(x_i)\right)_{1 \le i \le n-1}, \ U = (U_i)_{1 \le i \le n-1}$$

If we write v as a linear combination of basis elements of  $S : v = \sum_i V_i \phi_i$  with  $V_i = v(x_i)$  and denote  $V = (v(x_i))_{1 \le i \le n-1}$  we see that by linearity of a w.r.t. al components we have :

$$a(\tilde{u}_{S}, v) = a(\sum_{i} U_{i}\phi_{i}, \sum_{j} V_{j}\phi_{j}) = \sum_{i} \sum_{j} a(\phi_{j}, \phi_{i})U_{i}V_{j} = (\mathbf{K}U, V)$$
$$= (\mathbf{F}U, V) = \sum_{i=0}^{n} \frac{h_{i} + h_{i+1}}{2}f(x_{i})v(x_{i}) = Q(fv).$$

The difference method is thus equivalent to a piecewise polynomial approximation where the right hand side is approximated with a trapezoidal rule.

#### Exercise 8.

Let Q be give by the previous exercise. Prove that :

$$\left|Q(w) - \int_{0}^{1} w(x)dx\right| \le Ch^{2} \sum_{i=1}^{n} \int_{x_{i-1}}^{x_{i}} |w''(x)|dx$$
(3)

Hint : Observe that the trapezoidal rule is exact for piecewise linears and then use exercise 5.

**Answer**. Let  $w_I \in S$  be the piecewise linear interpolant of w. We have that the trapezoidal rule is exact for  $w_I$  and since  $w_I(x_i) = w(x_i)$  we have :

$$\int_0^1 w_I(x) dx = Q(w_I) = Q(w).$$

If we denote by  $e = w - w_I$  the equation (3) becomes :

$$\left| \int_{0}^{1} e(x) dx \right| \le Ch^{2} \sum_{i=1}^{n} \int_{x_{i-1}}^{x_{i}} |e''(x)| dx$$

By using the *homogeneity argument* it is enough to prove that :

$$\left| \int_{x_{i-1}}^{x_i} e(x) dx \right| \le C(x_i - x_{i-1})^2 \int_{x_{i-1}}^{x_i} |e''(x)| dx \Leftrightarrow \left| \int_0^1 \tilde{e}(t) dt \right| \le C \int_0^1 |\tilde{e}''(t)| dt$$

where  $\tilde{e}(t) = e(x_{i-1} + t(x_i - x_{i-1}))$ . To simplify the notations we denote  $w = \tilde{e}$  and we see that w(0) = w(1) = 0 and by Rolle's theorem there exist  $\xi$  such that  $w(\xi) = 0$ . We further obtain that :

$$\begin{aligned} \left| \int_{0}^{1} w(x) dx \right| &= \left| \int_{0}^{1} \int_{0}^{x} w'(t) dt dx \right| = \left| \int_{0}^{1} \int_{0}^{x} \int_{\xi}^{t} w''(\tau) d\tau dt dx \right| \le \int_{0}^{1} \int_{0}^{x} \left| \int_{\xi}^{t} w''(\tau) d\tau \right| dt dx \\ &\le \int_{0}^{1} \int_{0}^{1} \left| \int_{\xi}^{t} w''(\tau) d\tau \right| dt dx = \int_{0}^{1} \left| \int_{\xi}^{t} w''(\tau) d\tau \right| dt \\ &\le \int_{0}^{\xi} \int_{t}^{\xi} |w''(\tau)| d\tau dt + \int_{\xi}^{1} \int_{\xi}^{t} |w''(\tau)| d\tau dt \le \int_{0}^{\xi} \int_{0}^{\xi} |w''(\tau)| d\tau dt + \int_{\xi}^{1} \int_{\xi}^{1} |w''(\tau)| d\tau dt \\ &\le \xi \int_{0}^{\xi} |w''(\tau)| d\tau + (1-\xi) \int_{\xi}^{1} |w''(\tau)| d\tau \le \max\{\xi, 1-\xi\} \int_{0}^{1} |w''(x)| dx \end{aligned}$$

The constant is then given by :  $C = \max{\{\xi, 1 - \xi\}}.$ 

#### Exercise 9.

Let  $u_S$  the solution of  $a(u_S, v) = (f, v), \forall v \in S$ , where S consists of piecewise linears and let  $\tilde{u}_S$  be as in exercise 7. Prove that :

$$|a(u_S - \tilde{u}_S, v)| \le Ch^2(||f'|| + ||f''||)(||v|| + ||v'||)$$
(4)

Hint : Apply exercise 8 and Schwarz' inequality.

Answer. By applying exercises 7 and 8 we get :

$$\begin{aligned} |a(\tilde{u}_S - u_S, v)| &= |Q(fv) - (f, v)| = \left| Q(fv) - \int_0^1 (fv)(x) \right| &\le Ch^2 \int_0^1 |(fv)''(x)| dx \\ &= Ch^2 \int_0^1 |f''(x)v(x) + 2f'(x)v'(x)| dx \end{aligned}$$

By applying Schwarz's inequality we further obtain :

$$\begin{split} \int_{0}^{1} |f''(x)v(x) + 2f'(x)v'(x)|dx &\leq \int_{0}^{1} |f''(x) \cdot v(x)|dx + \int_{0}^{1} |f'(x) \cdot v'(x)|dx + \int_{0}^{1} |1 \cdot f'(x)v'(x)|dx \\ &\leq \|f''\|\|v\| + \|f'\|\|v'\| + \|f'v'\| \leq \|f''\|\|v\| + \|f'\|\|v'\| + C\|(f'v')'\| \\ &= \max\{1, C\}(\|f''\|\|v\| + \|f'\|\|v'\| + \|f''\|\|v'\| + \|f''\|\|v'\| \\ &\leq max\{1, C\}(\|f''\|\|v\| + \|f'\|\|v'\| + \|f''\|\|v'\| + \|f''\|\|v\|) \\ &\leq C(\|f'\| + \|f''\|)(\|v\| + \|v'\|) \end{split}$$

## Exercise 10.

Let  $u_S$  and  $\tilde{u}_S$  be like in the exercise 9. Prove that :

$$||u_S - \tilde{u}_S||_E \le Ch^2(||f'|| + ||f''||)$$

Hint : Apply exercise 9, pick  $v = u_S - \tilde{u}_S$  and apply exercise 6.

**Answer**. We plug  $v = u_S - \tilde{u}_S$  into (4) and we get :

$$||u_S - \tilde{u}_S||_E^2 = a(u_S - \tilde{u}_S, u_S - \tilde{u}_S) \le Ch^2(||f'|| + ||f''||)(||u_S - \tilde{u}_S|| + ||u'_S - \tilde{u}'_S||)$$

The coercivity of a (the application of the exercise 6) gives :

$$||u_S - \tilde{u}_S|| \le C ||u_S - \tilde{u}_S||_E$$
 and  $||u'_S - \tilde{u}'_S|| \le C ||u_S - \tilde{u}_S||_E$ 

and the conclusion follows directly.